Motion Planning HW 3: Trajectory Optimization using CasADi

Will Graham

# Reaching Desired Task Space Positions

Text, letter

Description automatically generated

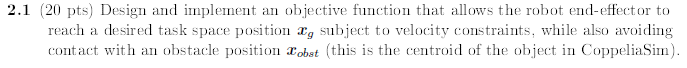
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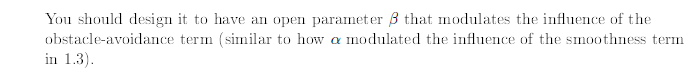
Description automatically generated

Text

Description automatically generated

# Obstacle Avoidance







Text

Description automatically generated